



# A Pareto Optimal Solution for Environmental/Economic Power Dispatch using Multi-objective Genetic Algorithm

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#### **Abstract**

The aim of this paper is to apply genetic algorithm (GA) to the solution of the environmental economic power dispatch problem. The environmental economic power dispatch is a multi-objective optimization problem. Fuel cost is considered as one of the objectives. The other objective is emissions such as SO2 or NOx or a combination of both. A trade-off relation between fuel cost and emissions can be formed through a pareto optimal front. Valve point opening and prohibited operating zones add non-smoothness and non-convexities to the objective functions. Evolutionary algorithms can efficiently solve such non-smooth and non-convex problems. Solutions need to be diversified and distributed among the whole range of the pareto optimal front. This allows operators to trade-off between fuel cost and emissions in feasible optimal regions. Applying genetic algorithm with diversity enhancement proves its effectiveness. Application of the algorithm on three and six unit systems is demonstrated.

**Keywords:** Genetic algorithms, Evolutionary programming, Environmental economic power dispatch, Non-convex functions, Non-smooth functions

#### 1. Introduction

The environmental economic power dispatch is a multi-objective optimization problem. Fuel cost is considered as one of the objectives. Emissions such as SO2 and NOx are the other objectives. The multi objectives are traditionally combined into a single objective through weighting factors. Many researchers solved the smooth and convex environmental economic power dispatch problem by classical optimization methods based on linear and non-linear programming techniques [1, 2]. However, prohibited operating zones (POZ) and valve point loading create non-smooth and non-convex objective functions. This causes difficulties in solving the economic power dispatch problem by classical methods. Evolutionary algorithms are efficiently used to solve non-smooth and non-convex environmental economic power dispatch problems. Genetic algorithms (GA) for such problems has been used in [8, 12, 14, 22]. Others used particle swarm optimization (PSO) in [11, 13, 15, 16, 27]. Differential evolution (DE) is used in [17, 21, 26]. Artificial neural networks (ANN) are used in [5, 6]. Fuzzy set theory and interactive fuzzy satisfying methods are used in [3, 24, 26]. Stochastic methods are used in [1, 11]. A surrogate worth trade-off algorithm is used in [4]. Hybrid algorithms are used in [18, 19, 20, 23, 28, 30]. Evolutionary algorithms are used in [7, 9, 10]. A harmony search method is used in [25]. Hony bee mating is used in [24]. Backtracking search optimization is used in [29]. In this paper, a genetic algorithm with diversity enhancement is applied to solve the environmental economic power dispatch problem. The proposed method is applied to power systems of different scales that have been intensively

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the subject of research in literature. Simulation results are compared with results reported in literature. The results prove that the genetic algorithm based environmental economic dispatch (GAEED) with diversity enhancement technique is comparable with other successful evolutionary techniques to solving the non-smooth and non-convex environmental economic power dispatch problems.

## 2. Economic Emissions Power Dispatch

The economic emissions power dispatch (EEPD) involves the minimization of two objectives subject to equality and inequality constraints.

# 2.1. Objectives

The first objective is the total fuel cost. The fuel cost function is

$$C = \sum_{k=1}^{NG} C_k \tag{1}$$

$$C_k = a_k + b_k P_k + c_k P_k^2 + \left| e_k \sin(f_k (P_k - P_{k_{\min}})) \right|$$
 (2)

The second objective is the total emissions. The emissions function is

$$E = \sum_{k=1}^{NG} E_k \tag{3}$$

$$E_k = \alpha_k + \beta_k P_k + \gamma_k P_k^2 + \xi_k \cdot \exp(\lambda_k \cdot P_k)$$
(4)

# 2.2. Equality constraints

The equality constraints are simplified to total active power balance equation

$$\sum_{k=1}^{NG} P_k - P_D - P_L = 0 ag{5}$$

where P<sub>D</sub> is total power demand and P<sub>L</sub> is transmission losses.

$$P_L = \mathbf{P}^{\mathsf{T}} \mathbf{B}_2 \mathbf{P} + \mathbf{B}_1 \mathbf{P} + \mathbf{B}_0 \tag{6}$$

#### 2.3 Inequality constraints

These are minimum and maximum limits on power generation and prohibited operating zones.

$$P_{k_{-\min}} \le P_k \le P_{k_{-\max}}$$
  $k = 1, 2, ...., NG$  (7)

$$P_{k_{-U_{j}}} \le P_{k} \le P_{k_{-L_{j+1}}}$$
  $j = 1,...,NZ_{k}, k = 1,...,NG$  (8)

where L<sub>i</sub> and U<sub>i</sub> are lower and upper bounds of prohibited operating zone j.

### 3. Multi-objective Optimization

Two objectives may be combined through a weighting factor to form a single combined objective as given by (9) that can be optimized easily.

$$F = \alpha F_1 + (1 - \alpha)F_2 \tag{9}$$

A trade-off relation is obtained if the weighting factor is adjusted for the whole range (0-1) as depicted in Figure 1. This is the pareto-optimal front which dominates all feasible solutions.

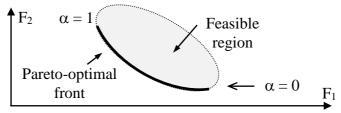


Figure 1: Pareto-optimal front

## 4. Genetic Algorithm Based Economic Emissions Power Dispatch

Genetic algorithms are population based searching techniques. It starts by initializing a population set known as parents. Parents undergo several operations to produce offspring. The process is continued for several generations. The produced offspring become the parents for the next generation. The basic operations are selection, crossover and mutation. Other operations to enhance the quality of the solutions can be included. Members of the population are known as chromosomes. Each chromosome consists of genes representing the variables of the problem. Variables are suitably coded for crossover and mutation. Real coding is implemented in this study. Each chromosome consists of the output power of the generators.

#### 4.1 Selection

Population is sorted based on the non-dominance sorting of the objectives. The sorting assigns a class number to each chromosome. The class number represents the number of dominating chromosomes to the specified chromosome. A diversity evaluation to each class is added to the class number to form the fitness function. A population of six chromosomes are shown in Figure 2. The diversity measure is the reciprocal of the distance between the chromosome and its left neighbour. The integer part between the brackets represents the class number while the decimals represent the diversity measure. The population is divided into two groups for crossover.

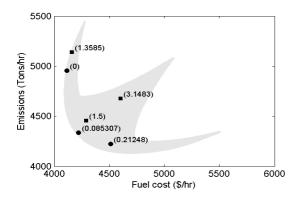


Figure 2: Population sorting

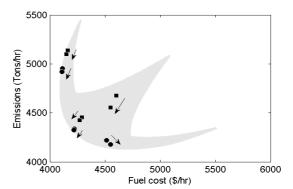


Figure 3: Crossover operation

#### 4.2. Crossover

The crossover operation aims to bring members closer to the pareto-optimal front. Members of the second group are moved closer to the first. Members of the first group are pushed away from the second. Members in the second group are mated with members in the first using (10).

for each k if rand  $< p_{cross}$ 

$$f_{diff_{index}} = min \left( \sqrt{(f_{1_{par_2}} + f_{1_{par_1}} + (f_{2_{par_2}} + f_{2_{par_1}} + f_{2_{par_1}} + (f_{2_{par_2}} + f_{2_{par_1}} + f_{2_{par_1}} + f_{2_{par_2}} + f_{2_{par_1}} + f_{2_{par_1}}$$

$$P_{diff} = P_{par_2_k} - P_{par_1_{index}}$$
(11)

$$P_{par_1_{index}} = P_{par_1_{index}} - k_{cross} \cdot P_{diff}$$
(12)

$$P_{par_2_k} = P_{par_2_k} - k_{cross} \cdot P_{diff}$$
(13)

where f1\_par\_1 and f2\_par\_1 represent the objectives of the first group while f1\_par\_2 and f2\_par\_2 represent the objectives of the second group. Selected chromosome genes are adjusted through (12) and (13). k<sub>cross</sub> is a user defined parameter of a positive value less than unity. The crossover operation for the population sorted in Figure 2 is shown in Figure 3.

## 4.3. Parents and offspring mating to enhance parents diversity

Parents diversity is enhanced by selecting the member from the parents with least distance from its neighbour. This member is replaced by a member that can be located between the two members with highest distance between them. The new member location is

$$P_{\text{new}} = k_1 \cdot P_k + k_2 \cdot P_i + k_3 \cdot P_m \tag{14}$$

where k<sub>1</sub>, k<sub>2</sub> and k<sub>3</sub> are weights having the sum of unity.

## 4.4. Parents and offspring combination

Parents and offspring are combined and sorted according to the non-dominance criterion to form a population of twice the original population number. The best  $N_{pop}$  number of the combination is selected to survive and proceed for mutation.

#### 4.5. Mutation

Population members are selected for mutation with a mutation probability. The selected member is mutated using (15) and replaces the member that it most dominates using (16).

$$P_{\text{mut}} = P_k + k_{\text{mut}} \cdot (\text{rand} - 0.5) \qquad \text{if rand } < p_{\text{mut}}$$
 (15)

for all k with  $\,f1\_mut < f1\_k$  and  $\,f2\_mut < f2\_k \,\,k = 1$  :  $N_{_{pop}}$ 

$$f_{diff_{j}} = max \left( \sqrt{(f1_{mut} - f1_{k})^{2} + (f2_{mut} - f2_{k})^{2}} \right)$$
 (16)

$$P_{_{j}} \Leftarrow P_{_{mut}}$$

### 4.6. Pareto-optimal front boundaries modification

The pareto-optimal front extremes contain two members. One has least fuel cost and highest emissions. The other has highest cost and least emissions. Both are improved as follows

$$P_{\text{temp1}} = P_{k1} + k_b \cdot \text{rand} \cdot \left(P_{k1} - P_{n1}\right) \quad \text{and} \qquad P_{\text{temp2}} = P_{k2} + k_b \cdot \text{rand} \cdot \left(P_{k2} - P_{n2}\right)$$
 (17)

$$P_{k1} \leftarrow P_{temp1} \quad \text{if } f_1(P_{temp1}) \ge f_1(P_{k1}) \text{ and } f_2(P_{temp1}) \le f_2(P_{k1})$$

$$\tag{18}$$

$$P_{k2} \leftarrow P_{temp2} \quad \text{if } f_1(P_{temp2}) \le f_1(P_{k2}) \text{ and } f_2(P_{temp2}) \ge f_2(P_{k2})$$

$$\tag{19}$$

where k1 represents the member of highest fuel cost and least emissions while k2 is the member of least fuel cost and highest emissions. Members n1 and n2 are the closest members.

## 4.7 Diversity Enhancement

Diversity enhancement is activated at the end of mutation. Each member is moved to the centre between its neighbours by replacing its variables by the mean of both as in (20).

$$P_{k} = 0.5(P_{n1} + P_{n2}) \tag{20}$$

## 4.8 Feasibility satisfaction

The power mismatch is determined when chromosomes are changed due to GA operations. Chromosomes are iteratively adjusted to satisfy the power balance using (21) and (22).

$$\Delta P_k = \sum_{j=1}^{NG} P_{jk} - P_D - P_L \tag{21}$$

$$P_{k} = P_{k} - \Delta P_{k} / NG \tag{22}$$

where  $\Delta P_k$  is the power mismatch of chromosome k and  $P_{jk}$  are elements of vector  $P_k$  representing the output power of generators.  $P_L$  denotes the transmission losses defined by (6).

## 5. Simulation

The algorithm has been tested on two different systems. These systems consist of 3 and 6 units which have been the subject of intensive research in literature. The number of population used is 100 for all simulations. The crossover and mutation probabilities are set to 0.80 and 0.20 respectively.

## 5.1. 3-Units system

Fuel cost and emission parameters together with generation limits and prohibited zones are shown in Tables 1 and 2. Demand is 850.0 MW. Losses B-coefficients are in [10]. Two cases have been studied. One neglects prohibited zones (POZ) while the other includes them. Results are shown in Table 3 and Figure 4-7.

# 5.2. 6-Units system

Fuel cost and emission parameters together with generation limits and prohibited zones are shown in Tables 4 and 5. Demand is 2.834pu (100MVA base). Losses B-coefficients are in [18]. Two cases have been studied. One neglects prohibited zones (POZ) while the other includes them. Results are shown in Table 6 and Figure 8-9.

Table 1: Three units cost parameters and operating limits

Fuel cost parameters						Generat	ion limits	POZ l	imits
Unit	a(\$/hr)	b(\$/MW/hr)	$c(\frac{MW^2}{hr})$	e(\$/hr)	f(1/MW)	Pmin(MW)	Pmax(MW	)POZ1(MW)	POZ2(MW)
1	561.0	7.9200	0.001562	200.0	0.0180	150.0	600.0	[200 210]	[510 520]
2	310.0	7.8500	0.001940	200.0	0.0220	100.0	400.0	[180 190]	[280 290]
3	78.0	7.9700	0.004820	60.0	0.0460	50.0	200.0	[60 70]	[85 95]

Table 2: Three units emission parameters

	SC	02 emission par	rameters	NOx emission parameters			
Unit	α(Ton/hr)	β(Ton/MW/hr)	γ(Ton/MW <sup>2</sup> /hr)	α(Ton/hr)	β(Ton/MW/hr)	γ(Ton/MW <sup>2</sup> /hr)	
1	0.5783298	8.16466e-3	1.6103e-6	0.043732540	-9.4868099e-5	1.4721848e-7	
2	0.3515338	8.91174e-3	2.1999e-6	0.055821713	-9.7252878e-5	3.0207577e-7	
3	0.0884504	9.03782e-3	5.4658e-6	0.027731524	-3.5373734e-4	1.9338531e-6	

Table 3: Three units solution with valve point loading and prohibited operating zones

	Minimum fuel cost		Minimum S	O2 emissions	Minimum NOx emissions	
Method	VPL	VPL and POZ	VPL	VPL and POZ	VPL	VPL and POZ
P1 (MW)	512.325262	520.000000	552.684014	522.522383	508.686446	508.894654
P2 (MW)	<u>285.599225</u>	275.532730	219.151506	247.253678	250.326563	250.140565
P3 (MW)	<u>67.843174</u>	70.000000	92.681444	95.000000	105.731044	105.706176
Ploss (MW)	15.767661	15.532730	14.516964	14.776061	14.744054	14.741396
Fuel cost (\$/hr)	8421.249722	8443.074225	8749.826861	8583.843045	8617.616010	8617.601894
SO2 (Tons/hr)	8.986879	8.981281	8.965938	8.970063	8.983458	8.973555
Nox (Tons/hr)	0.099062	0.098613	0.128420	0.096179	0.095924	0.095924

Table 4: Six units cost parameters and limits

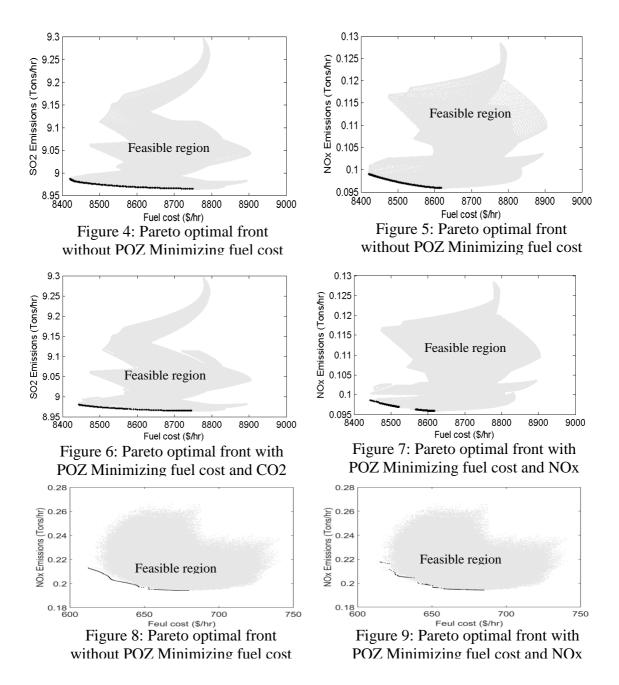
Fuel cost parameters					Generation limits		POZ limits		
Unit	a(\$/hr)	b(\$/MW/hr)	$c(\frac{MW^2}{hr})$	e(\$/hr)	f(1/MW)	Pmin(pu)	Pmax(pu)	POZ1(pu)	POZ2(pu)
1	10	200	100	15	6.283	0.0500	0.5000	[0.10 0.20]	[0.30 0.40]
2	10	150	120	10	8.976	0.0500	0.6000	$[0.10 \ 0.20]$	$[0.30 \ 0.40]$
3	20	180	40	10	14.784	0.0500	1.0000	[0.20 0.30]	$[0.80 \ 0.90]$
4	10	100	60	5	20.944	0.0500	1.2000	[0.20 0.30]	$[0.80 \ 0.90]$
5	20	180	40	5	25.133	0.0500	1.0000	[0.20 0.30]	$[0.50 \ 0.60]$
6	10	150	100	5	18.480	0.0500	0.6000	$[0.10 \ 0.20]$	$[0.30 \ 0.40]$

Table 5: Six units NOx emission parameters

Unit	α(Ton/hr)	$\beta(Ton/MW/hr)$	$\gamma$ (Ton/MW <sup>2</sup> /hr)	ζ(Ton/hr)	$\lambda(1/MW)$
1	0.04091	-0.05554	0.06490	2.0e-4	2.857
2	0.02543	-0.06047	0.05638	5.0e-4	3.333
3	0.04258	-0.05094	0.04586	1.0e-6	8.000
4	0.05326	-0.03550	0.03380	2.0e-3	2.000
5	0.04258	-0.05094	0.04586	1.0e-6	8.000
6	0.06131	-0.05555	0.05151	1.0e-5	6.667

Table 6: Six units solution with valve point loading and prohibited operating zones

	Minimu	m fuel cost	Minimum NOx emissions		
Method	VPL	VPL and POZ	VPL	VPL and POZ	
P1 (pu)	0.050002	0.050000	0.410788	0.098948	
P2 (pu)	0.395717	0.400000	0.463542	0.419641	
P3 (pu)	0.687492	0.686254	0.544392	0.683814	
P4(pu)	0.800042	0.900000	0.390354	0.600543	
P5 (pu)	0.550046	0.421241	0.544412	0.633717	
P6 (pu)	0.372890	0.400000	$\overline{0.515371}$	0.418566	
Ploss (pu)	0.022189	0.023495	0.034859	0.021233	
Fuel cost (\$/hr)	612.3612	615.2387	679.6607	636.7332	
Nox (Tons/hr)	0.212999	0.217699	0.194178	0.204650	



#### 6. Conclusions

A genetic algorithm based environmental economic power dispatch with diversity enhancement (GAEED) is proposed in this paper. A genetic algorithm is an evolutionary algorithm that relies on mating between chromosomes to produce offspring. The operations of a genetic algorithm are selection, crossover and mutation. In this paper, a genetic algorithm is used to solve the multi-objective optimisation of the environmental economic power dispatch problem. Population of the genetic algorithm evolve to discover the pareto optimal front of the feasible solutions. The problem is non-smooth and non-convex due to

prohibited operating zones and valve point opening. A diversity enhancement aiming to diversify the solutions among the pareto optimal front to cover the whole front is proposed. The proposed algorithm has been simulated on three and six unit systems with transmission losses and non-smooth objective functions.

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